

## DAFTAR PUSTAKA

- [1] I. Mutiara Kami, "Kisah Heroik Penyelam Tukar Nyawa dengan 13 Korban di Gua Thailand." [Online]. Available: <https://news.detik.com/internasional/4108144/kisah-heroik-penyelam-tukar-nyawa-dengan-13-korban-di-gua-thailand>. [Accessed: 10-Jul-2018].
- [2] "Kronologi Penyelamatan 12 Remaja Thailand yang Hilang di Gua," 2018. [Online]. Available: <https://www.cnnindonesia.com/internasional/20180703132812-106-311086/kronologi-penyelamatan-12-remaja-thailand-yang-hilang-di-gua>. [Accessed: 02-Apr-2019].
- [3] Y. Liu, P. Huang, F. Zhang, and Y. Zhao, "Robust distributed consensus for deployment of Tethered Space Net Robot," *Aerospace Sci. Technol.*, vol. 77, pp. 524–533, 2018.
- [4] Z. Peng, S. Yang, G. Wen, and A. Rahmani, "Distributed consensus-based robust adaptive formation control for nonholonomic mobile robots with partial known dynamics," *Math. Probl. Eng.*, vol. 2014, 2014.
- [5] Z. Peng, S. Yang, G. Wen, A. Rahmani, and Y. Yu, "Adaptive distributed formation control for multiple nonholonomic wheeled mobile robots," *Neurocomputing*, vol. 173, pp. 1485–1494, 2016.
- [6] M. Maghenem, A. Bautista-Castillo, E. Nuño, A. Loría, and E. Panteley, "Consensus-based Formation Control of Nonholonomic Robots using a Strict Lyapunov Function," *IFAC-PapersOnLine*, vol. 50, no. 1, pp. 2439–2444, 2017.
- [7] J. W. Kwon and D. Chwa, "Hierarchical Formation Control Based on a Vector Field Method for Wheeled Mobile Robots," *Robot. IEEE Trans.*, vol. 28, no. 6, pp. 1335–1345, 2012.
- [8] Z. Peng, G. Wen, A. Rahmani, and Y. Yu, "Distributed consensus-based formation control for multiple nonholonomic mobile robots with a specified reference trajectory," *Int. J. Syst. Sci.*, vol. 46, no. 8, pp. 1447–1457, 2015.
- [9] A. Galbis and M. Maestre, "Vector Analysis Versus Vector Calculus - Antonio Galbis, Manuel Maestre - Google Buku." [Online]. Available: [https://books.google.co.id/books?id=tdF8uTn2cnMC&pg=PA12&redir\\_esc=y#v=onepage&q&f=false](https://books.google.co.id/books?id=tdF8uTn2cnMC&pg=PA12&redir_esc=y#v=onepage&q&f=false). [Accessed: 04-Feb-2019].
- [10] D. R. Nelson, D. B. Barber, T. W. McLain, S. Member, R. W. Beard, and S. Member, "Vector Field Path Following for Miniature Air Vehicles," vol. 23, no. 3, pp. 519–529, 2007.
- [11] W. Ren and R. W. Beard, *Distributed Consensus in Multi-vehicle Cooperative Control* .



جامعة  
الإسلامية  
الإندونيسية