

APPENDIX

Tecnomatix coding for the model:

- The setting of parts that has been assembled
`waituntilAssembly.Occupiedprio 1;@.move`

- The summary list of station time

`TaskTime_List[2,1]:=Station1_EF1.ProcTime+2;TaskTime_List[2,2]:=Station1_LH1.P
 rocTime+2;.....TaskTime_List[3,26]:=Station10_LH2.ProcTime+2;TaskTime_List[
 3,27]:=Station10_EB2.ProcTime+2;`

- Tasks placement

`TableFile1[2,1]:=Station1_EF1.ProcTime+2;TableFile1[2,2]:=Station1_EF2.ProcTime
 +2;.....TableFile27[2,1]:=Station10_EB1.ProcTime+2;TableFile27[2,2]:=Station10
 _EB2.ProcTime+2;`

- The overall proportion of units produced (qm)

`qm_Model_A:=(Model_A_Innova/TotalDemand);
 qm_Model_B:=(Model_B_Fortuner/TotalDemand);`

-Calculation of task time total

`TOTAL_TASK_TIME_INNOVA:=TableFile1[2,1]+.....+TableFile27[2,1]
 TOTAL_TASK_TIME_FORTUNER:=TableFile1[2,2]+.....+TableFile27[2,2]`

- Waiting time

`WaitingTime_List[2,1]:=Cycle_Time-
 (Station1_EF1.ProcTime+2);.....WaitingTime_List[2,27]:=Cycle_Time-
 (Station10_EB2.ProcTime+2);WaitingTime_List[3,1]:=Cycle_Time-`

$(Station1_EF1.ProcTime+2); \dots \dots \dots WaitingTime_List[3,27]:=Cycle_Time-$
 $(Station10_EB2.ProcTime+2);$
 $WaitingTime_List[4,1]:=WaitingTime_List[2,1]+ \dots \dots \dots +WaitingTime_List[2,27];$
 $WaitingTime_List[5,1]:=WaitingTime_List[3,1]+ \dots \dots \dots +WaitingTime_List[3,27];$

- Weighted line efficiency

$Weighted_Line_Efficiency_Percentages:=((qm_Model_A*(TOTAL_TASK_TIME_IN$
 $NOVA)/(Cycle_Time*NumberofWorkstations))+ (qm_Model_B*(TOTAL_TASK_TIM$
 $E_FORTUNER)/(Cycle_Time*NumberofWorkstations)))*100;$

- Weighted smoothness index

$Weighted_Smoothness_index:=sqrt((qm_Model_A*((TaskTimeList[2,1]-$
 $TaskTime_List[3,9])*(TaskTime_List[2,1]-$
 $TaskTime_List[3,9])+ \dots \dots \dots +(TaskTime_List[2,27]-$
 $TaskTime_List[3,9])*(TaskTime_List[2,27]-$
 $TaskTime_List[3,9]))/27)+sqrt((qm_Model_B*((TaskTime_List[3,1]-$
 $TaskTime_List[3,9])*(TaskTime_List[3,1]-$
 $TaskTime_List[3,9])+ \dots \dots \dots +(TaskTime_List[3,27]-$
 $TaskTime_List[3,9])*(TaskTimeList[3,27]-TaskTime_List[3,9]))/27);$

- Cycle time constraint

$CT_Max:=Planning_Horizon/TotalDemand;$
 $CT_Min:=(qm_Model_A*(TOTAL_TASK_TIME_INNOVA))/27+(qm_Model_B*(TO$
 $TAL_TASK_TIME_FORTUNER))/27;$

Optimization program of MTALB type II problem:

is

$i,k,m:$ integer;

station:object;

startX,startY:integer;

p:object;

contCells:integer;

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tab:table[string,time];
remProcTime:time;
row:integer;
preds:list;
assigned:boolean;
do
startX:=240;
startY:=240;
p:=source;
tab.create;
partData.delete({3,1}..{3,*});
--clean the old version from source, drain, station
for i:= self.~.numNodesdownto 1 loop
    ifself.~.node(i).class.name="Drain" or
    self.~.node(i).class.name="Station" then
        self.~.node(i).deleteObject;
    end;
next;
--create all stations from partData from Col 4++
for i:=4 to partData.xDim loop
    --create a new station
station:=.ApplicationObjects.UserObjects.Station.createObject(self.~,startX,starty);
station.name:=partData[i,0];
startX:=startX+60;
.MaterialFlow.Connector.connect(p,station);
p:=station;
--look for not assigned parts
--prio 1. MUST assembled here --field Station,part is occupied and number of
filled cells right until xDim is zero
for k:=1 to partData.ydim loop
    --not assigned
    ifpartData[3,k] = void and partData[Station.name,k] /= void then
        --marked

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--look at all other cols in this row
contCells:=0;
for      m:=      partData.getColumnNo(Station.name)+1      to
partData.xdim loop
    ifpartData[m,k] /= void then
        contCells:=contCells+1;
    end;
next;
ifcontCells=0 then
    --must be assembled here !!
    partData[3,k]:=station.name;
station.workContent.writeRow(1,station.workContent.yDim+1,partData[1,k],partData[2
,k]);
    end;
end;
next;
--prio 2. Search for the part with the lowest number of alternatives and max
possible assembly time
--write all possible parts into a table [part, time, num alternatives]
tab.delete;
remProcTime:=root.cycleTime- station.workcontent.sum({2,1}..{2,*});
for k:=1 to partData.ydim loop
    --not assigned
    if station.name="Station3" then
        --      debug;
    end;
    ifpartData[3,k] = void and partData[Station.name,k] /= void then
        --write all possible operations into a table
        ifpartData[2,k] <= remProcTime then
            --check the position of the part in the assembly graph
            --all predessessors need to be assembled
            preds:=assemblyOrder.getPartPredecessors(partData[1,k]);
            --if the ist is empty, no predessor

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        if preds.dim=0 then
tab.writeRow(1,tab.yDim+1,partData[1,k],partData[2,k]);
        else
            --assign only parts, when all predecessors are
assigned
            assigned:=true;
            for m:=1 to preds.dim loop
                if partData[3,preds.read(m)] = void then
                    assigned:=false;
                end;
            next;
            if assigned=true then
tab.writeRow(1,tab.yDim+1,partData[1,k],partData[2,k]);
            end;
        end;
    end;
end;
next;
--sort tab second column "down"
--tab.sort(2,"down"); sort mixes the assembly order
--fill the station with content
for m:=1 to tab.yDim loop
    --check remaining cycle time
    remProcTime:=root.cycleTime- station.workcontent.sum({2,1}..{2,*});
    if remProcTime>=tab[2,m] then
        --assign to station
        partData.setCursor(1,1);
        partData.find({1,1}..{1,*},tab[1,m]);
        partData[3,partData.cursorY]:=station.name;
        --write part in work content
station.workContent.writeRow(1,station.workContent.yDim+1,tab[1,m],tab[2,m]);
    end;
next;

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--set the sum of assembly times as processTime of the station
station.procTime:=station.workcontent.sum({2,1}..{2,*});
next;
--connect the last station with a drain
p:=.MaterialFlow.Drain.createObject(self.~,startX,starty);
.MaterialFlow.Connector.connect(station,p);end;
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