

Daftar Pustaka

- Ademu, I. O., Imafidion, C. O., & Preston, D. S. (2011). A New Approach of Digital Forensic Model for Digital Forensic Investigation. *International Journal of Advanced Computer Science and Applications*, 2(12), 175–178. <http://doi.org/10.14569/IJACSA.2011.021226>
- Breu, F., Guggenbichler, S., & Wollmann, J. (2008). GLONASS Overview. *Vasa*, 1–7. Retrieved from <http://medcontent.metapress.com/index/A65RM03P4874243N.pdf>
- Clint, M. R., Reith, M., Carr, C., & Gunsch, G. (2002). An Examination of Digital Forensic Models. *International Journal of Digital Evidence*, 1(3), 1–12. <http://doi.org/10.1109/SADFE.2009.8>
- Cusack, B., & Simms, M. (2011). Evidential recovery from GPS devices. *Journal of Applied Computing and Information Technology*, 15(1). Retrieved from http://citrenz.ac.nz/JACIT/JACIT1501/2011Cusack_EvidentialRecovery.html
- DJI. (2015a). DJI Advance Specs. Retrieved from <http://www.dji.com/product/phantom-3-adv/info#specs>
- DJI. (2015b). Phantom 3 User Manual.
- Ganeshan, A. S., Rathnakara, S. C., Gupta, R., & Jain, A. K. (2005). Indian regional navigation satellite system (IRNSS) concept. *Journal of Spacecraft Technology*, 15(2), 19–23.
- Hartmann, K., & Steup, C. (2013). The vulnerability of UAVs to cyber attacks - An approach to the risk assessment. *Cyber Conflict (CyCon), 2013 5th International Conference on*, 1–23.
- Hay, B., Bishop, M., & Nance, K. (2009). Live analysis: Progress and challenges. *IEEE Security and Privacy*, 7(2), 30–37. <http://doi.org/10.1109/MSP.2009.43>
- Horsman, G. (2016). Unmanned aerial vehicles: A preliminary analysis of forensic challenges. *Digital Investigation*, 16, 1–11. <http://doi.org/10.1016/j.diin.2015.11.002>
- Huang, D. (2013). Evidential Problems with GPS Accuracy : Device Testing.
- Iswardani, A., & Riadi, I. (2016). DENIAL OF SERVICE LOG ANALYSIS USING DENSITY K-MEANS METHOD, 83(2), 299–302.
- Jiang, T., Li, J., & Huang, K. (2015). Longitudinal parameter identification of a small unmanned aerial vehicle based on modified particle swarm optimization. *Chinese Journal of Aeronautics*, 28(3), 865–873. <http://doi.org/10.1016/j.cja.2015.04.005>
- Lou, Y., & Wang, W. (2009). Map-Matching for Low-Sampling-Rate GPS Trajectories, (c).
- Lukmana, M. A., & Nurhadi, H. (n.d.). Rancang Bangun Unmanned Aerial Vehicle (UAV), 1–5.
- Nelson, B. (2011). IT Forensics, Inc., 2(1).
- Nishar, A., Richards, S., Breen, D., Robertson, J., & Breen, B. (2016). Thermal infrared imaging of geothermal environments and by an unmanned aerial vehicle (UAV): A case study of the Wairakei – Tauhara geothermal field, Taupo, New Zealand. *Renewable Energy*, 86, 1256–1264. <http://doi.org/10.1016/j.renene.2015.09.042>
- Nurdiansyah, M. (2011). Perancangan dan Implementasi Kontroler PID untuk Tracking Waypoint pada Sistem Navigasi UAV (Unmanned Aerial Vehicle) Berbasis GPS (Global Positioning System). *Seminar Tugas Akhir*, 1–8.
- Office, N. (2011). Development of BeiDou Navigation Satellite System. *Development*, (September), 882–912.
- Shao, H. (2015). Drone Overlord Frank Wang On DJI's Milestones, Miscarried GoPro Partnership & Corporate Espionage. *Forbes Asia*. Retrieved from <http://www.forbes.com/sites/forbesasia/2015/05/07/drone-overlord-frank-wang-on-djis-milestones-miscarried-gopro-partnership-corporate-espionage/>
- Song, Y. M., & Kwak, K. S. (2015). *Electronics, Information Technology and Intellectualization: Proceedings of the International Conference EITI 2014, Shenzhen*,

- China, 16-17 August 2014. CRC Press.
- Strawn, C. (2009). Expanding the Potential for GPS Evidence Acquisition. *Small Scale Digital Device Forensics Journal*, 3(1), 1–12.
- Sukriadi, & Prayudi, Y. (2014). Analisis Bukti Digital Global Positioning System (GPS) Pada Smartphone Android. *Kns&I Stikom*, (11).
- Valdman, J. (2001). Log File Analysis.

